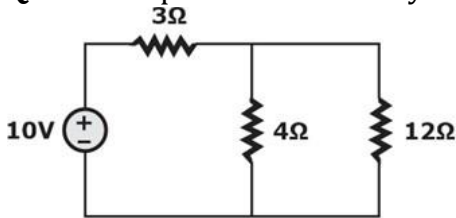


BTSC JE electrical Sample Paper

Q101. The power absorbed by the 3Ω resistor in the circuit given below is

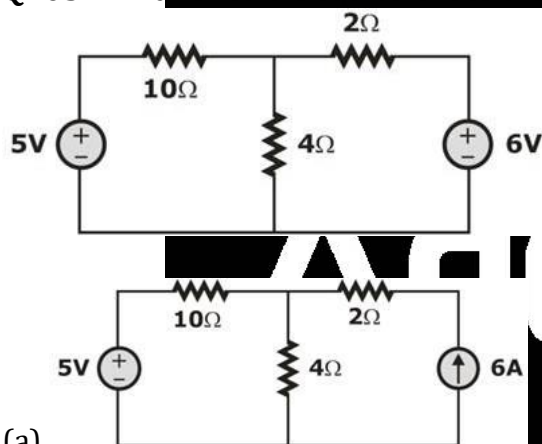


- (a) 833 W
(b) 83.3 W
(c) 5 W
(d) 8.33 W

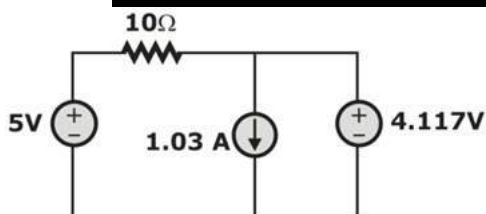
Q102. To g [REDACTED] findings of its secondary s [REDACTED]

- (a) Delta
(b) Parallel
(c) Star
(d) Series

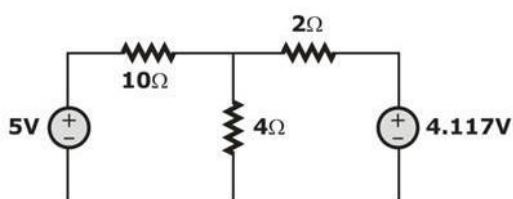
Q103. Which fruit sells in five



- (a)



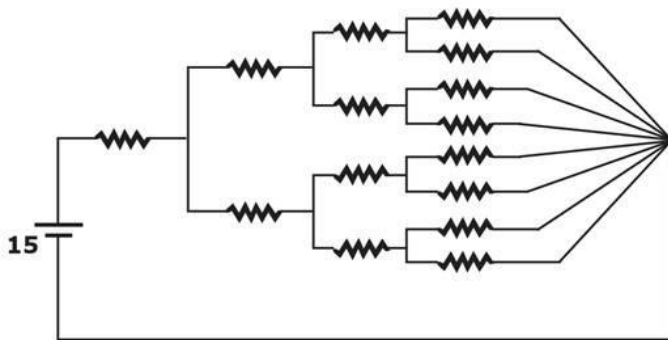
- (b)



- (c)

- (d) Both (b) and (c)

Q104. What is the current supplied by 15 V source when each resistance is 2 ohm?

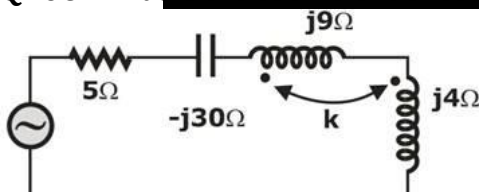


- (a) 4A
- (b) 2A
- (c) 1A
- (d) 3A

Q105. What is the average value of the voltage $v(t) = 50 \sin(\omega t)$ over one cycle? The voltage is measured in V and time in sec.

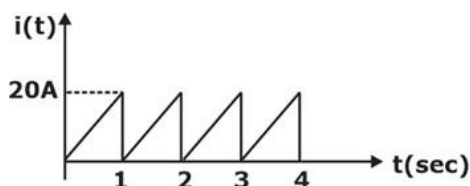
- (a) 25 V
- (b) 14.14 V
- (c) 353.5 V
- (d) 35.35 V

Q106. What is the average value of the current $i(t)$ in the given circuit?



- (a) 0.4
- (b) 1.416
- (c) 0.8
- (d) Resonance

Q107. A current waveform is shown below, if it is fed to an ac ammeter, what is the reading shown by the meter?



- (a) 20.2 A
- (b) 6.65 A
- (c) 14.14 A
- (d) 11.54 A

Q108. Which of the following theorems can be applied to any network linear or non-linear, active or passive, time variant or time invariant?

- (a) Norton theorem
- (b) Thevenin theorem
- (c) Tellegen theorem
- (d) Superposition theorem

Q109. In a series RLC circuit, if $X_C > X_L$, then the

- (a) Current and voltage will be in phase
- (b) Supply voltage will lead the current
- (c) Current will lead the voltage
- (d) Current will lag the voltage

Q110. The S.I. unit of conductance is

- (a) Coulomb
- (b) Ohm
- (c) Siemens
- (d) Newton

Q111. Which of the following is not a closed circuit? Proportional to the

- (a) Current loop
- (b) Voltage loop
- (c) Kirchhoff's law
- (d) Ohm's law

Q112. The potential inside a charged hollow sphere is

- (a) Zero
- (b) Same as on the surface
- (c) Less than on the surface
- (d) None of these

Q113. Paramagnetic materials have relative permeability

- (a) Slightly less than unity
- (b) Slightly more than unity
- (c) Equal to unity
- (d) Equal to that of ferromagnetic materials

Q114. Which of the following statements is true about magnetic lines of force?

- (a) Magnetic lines of force are always closed.
- (b) Magnetic lines of force always intersect each other.
- (c) Magnetic lines of force tend to crowd far away from the poles of the magnet.
- (d) Magnetic lines of force do not pass through the vacuum.

Q115. The RMS value of a half – wave rectified alternating current is 20A. its value for full-wave rectification will be: -

- (a) $\frac{40}{\pi}$ A
- (b) $\frac{80}{\pi}$ A
- (c) $\frac{40}{\sqrt{2}}$ A
- (d) 40 A

Q116. The energy used by a 2kW electric iron in 10 minutes is

- (a) 120 kJ
- (b) 12 kJ
- (c) 1200 kJ
- (d) 1.2 kJ

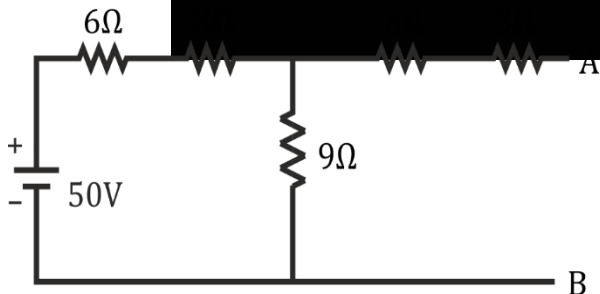
Q117. In a coil of length ℓ and area of cross-section A , the magnetic field will be-

- (a) Half
- (b) Double
- (c) Four times
- (d) No change

Q118. What is the magnetic field at the center of a circular coil of radius ℓ having N turns and carrying current I ?

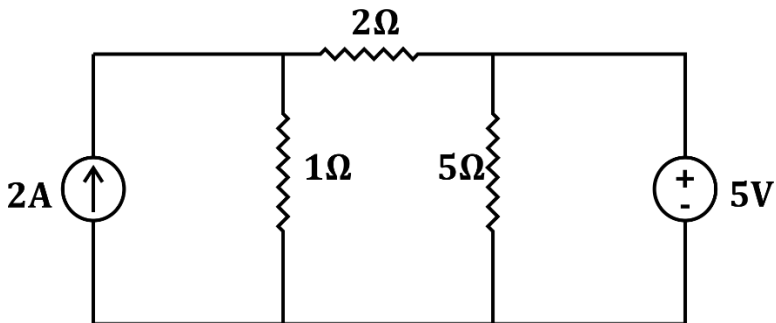
- (a) $H = NI\ell$
- (b) $H = \frac{NI}{\ell}$
- (c) $H = \frac{\ell}{NI}$
- (d) $H = \frac{NI^2}{\ell}$

Q119. What is the equivalent resistance between terminals A and B in the following electrical circuit.



- (a) 2.6 Ω
- (b) 7.9 Ω
- (c) 13.5 Ω
- (d) 15.4 Ω

Q120. Determine the current through the 5Ω resistor in the figure given below utilizing Thevenin's theorem.



- (a) 1A
- (b) 2A
- (c) 3A
- (d) 4A

Q121. Proximity effect

- (a) Reducing
- (b) Reducing
- (c) Increasing
- (d) Reducing

Q122. A generator has a maximum demand of 5 MW and a load factor of 0.6. If the load factor is 0.6 then the load factor will be

- (a) 0.25
- (b) 56
- (c) 0.56
- (d) 0.65

Q123. The Buchholz relay is used to protect the

- (a) Alternator
- (b) Oil immersed transformer
- (c) Synchronous motor
- (d) Transmission lines against all short circuit faults.

Q124. If for a string insulator system, voltage across bottom last unit is 25% of total string voltage with 5 units; its string efficiency is?

- (a) 80%
- (b) 85%
- (c) 90%
- (d) 20%

Q125. The surge impedance of 400 km long overhead transmission line is 300 ohm. For a 200 km length of the same transmission line surge impedance will be

-
- (a) 150 ohm
 - (b) 600 ohm
 - (c) 75 ohm
 - (d) 300 ohm

Q126. The rated slip of an induction motor at full load is 5% while the ratio of starting current to full load current is four. The ratio of the starting torque to full load torque would be

- (a) 0.6
- (b) 0.8
- (c) 1
- (d) 1.4

Q127. What is the angle between stator direct axis and quadrature axis of a reluctance motor?

- (a) 0°
- (b) 90°
- (c) 45°
- (d) None of above

Q128. A uni

- (a) Low speed
- (b) Low torque
- (c) High speed
- (d) None of

Q129. A 22 speed.

- (a) 1455 rpm
- (b) 728 rpm
- (c) 970 rpm
- (d) 960 rpm

Q130. When excitation, a

- (a) Increases
- (b) Decreases
- (c) Remains constant
- (d) None of above

Q131. Synchronous motor can be made self-starting by providing

- (a) Damper winding on rotor poles
- (b) Damper winding on stator
- (c) Damper winding on stator as well as rotor poles
- (d) None of above

Q132. A 12 Pole, 440V, 50Hz, 3-Phase 5 synchronous motor takes a line current of 100A at 0.8 pf leading. Neglecting losses, the torque developed will be?

- (a) 750 Nm
- (b) 1165 Nm
- (c) 1345 Nm
- (d) 1236 Nm

Q133. Hunting occurs in....

- (a) Synchronous motor
- (b) Synchronous generator
- (c) Transformer
- (d) Both synchronous motor and generator

Q134. A synchronous motor has

- (a) $P=10$, $f=50$ Hz
- (b) $P=12$, $f=50$ Hz
- (c) $P=6$, $f=50$ Hz
- (d) $P=10$, $f=60$ Hz

Q135. When the field current of a synchronous motor is switched Off, the motor will stop. The magnitude of the induced EMF is

- (a) Varies with speed
- (b) Varies with field current
- (c) Constant
- (d) None of the above

Q136. A three phase stack variable reluctance stepper motor has 12 poles in each rotor and stator stack. The step angle of this stepper motor is

- (a) 6 degree
- (b) 9 degree
- (c) 12 degree
- (d) 18 degree

Q137. The range of efficiency of shaded pole motor is

- (a) 90 to 100%
- (b) 50 to 70%
- (c) 80 to 90%
- (d) 5 to 35%

Q138. The highest transmission voltage used in India is

- (a) 400 kV
- (b) 220 kV
- (c) 132 kV
- (d) 765 kV

Q139. In AC transmission system the load current is

- (a) Independent of power factor
- (b) Directly proportional to power factor
- (c) Inversely proportional to power factor
- (d) None of the above

Q140. Stringing chart represents a graph of _____.

- (a) Sag and tension vs temperature
- (b) Sag vs supply frequency
- (c) Sag vs conductor size
- (d) Tension

Q141. In a transmission line

- (a) E^2
- (b) E
- (c) $1/E^2$
- (d) $1/E$

Q142. Corona loss in a transmission line is _____.

- (a) 10 times
- (b) Infinite
- (c) Zero
- (d) Less than

Q143. Among the following statements which one is true

- (a) DC transmission is more efficient
- (b) AC transmission is more efficient
- (c) Both are
- (d) High voltage

Q144. Skin effect

- (a) Supply frequency
- (b) Cross-sectional area of the conductor
- (c) Permeability of conductor material
- (d) All of above

Q145. The inductance of transmission line increase with

- (a) Increase in load current carried by the conductor
- (b) Increase in spacing between phase conductors
- (c) Decrease in line length
- (d) None of these

Q146. In AC distribution system the voltage can be controlled by using

- (a) Tap changing transformer
- (b) Booster transformer
- (c) Induction regulator
- (d) Any of the above

Q147. Bus Bar is rated by

- (a) Voltage only
- (b) Current only
- (c) Current, voltage and frequency
- (d) Current, voltage and length

Q148. The size of the

- (a) Armature
- (b) Ward Leonard
- (c) Field divider
- (d) Armature

Q149. In a DC motor, the speed is controlled by varying the

- (a) Constant
- (b) Variable
- (c) Constant
- (d) Variable

Q150. Which of the following is NOT used for controlling the speed of slip ring induction motor?

- (a) Cascaded pole method
- (b) Changing pole method
- (c) Slip power
- (d) Rotor resistance

Q151. Consider the following statements.

1. Surge impedance of a transmission line is independent of its length.
2. The size of conductor for modern EHV lines is determined on the basis of current density.
3. The insulation of EHV lines is designed on the basis of switching surges.
4. Synchronous compensation is being preferred over static compensation in EHV lines.

Which of the following statement is/is are correct?

- (a) 1 and 2 are correct
- (b) 1 and 3 are correct
- (c) 2 and 4 are correct
- (d) 3 and 4 are correct

Q152. When the two windings of a transformer are connected electrically, it is called as:

- (a) Auto transformer
- (b) Two winding transformer
- (c) Electrical transformer
- (d) Ideal transformer

Q153. A short circuit current in an alternator is

- (a) higher when fault occurs away from alternator
- (b) higher when fault occurs near to alternator
- (c) independent from the distance of fault occurs
- (d) None

Q154. Find the short circuit current of 2000 V, 1000 kVA, 92% efficiency, 0.02 pu reactance and base current of 2000 V, 1000 kVA is

- (a) 0.15 mA
- (b) 0.25 mA
- (c) 0.35 mA
- (d) 0.75 mA

Q155. _____ is a type of diode which is used in high frequency circuits.

- (a) Zener diode
- (b) Schottky diode
- (c) Tunnel diode
- (d) None of these

Q156. In DC motor, the armature reaction is significant at:-

- (a) the armature current is low
- (b) both the armature current and pole fluxes are high
- (c) the yoke is of cast iron
- (d) the pole shoes are of cast iron

Q157. For a three-phase induction motor, if the rotor resistance is increased, the motor is also

attached.

The induction motor will now operate at a

- (a) lagging
- (b) leading
- (c) reduced power factor
- (d) increased power factor

Q158. For a given three-phase induction motor, the slip at full load is

- (a) equal to slip at no-load
- (b) less than slip at no-load
- (c) greater than slip at no-load
- (d) equal to zero

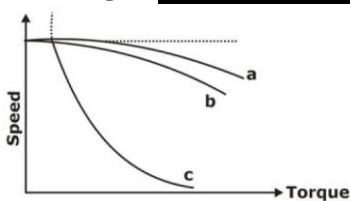
Q159. The armature resistance of a DC motor is 0.4, the supply voltage is 200V and the back emf. is 198V at full speed. The armature current is?

- (a) 4A
- (b) 8A
- (c) 5A
- (d) 0.5A

Q160. 2's complement of 2's complement of the binary number 10010101 will be

- (a) 01101010
- (b) 01101011
- (c) 10010100
- (d) 10010101

Q161. Speed



- (a) a
- (b) b
- (c) c
- (d) None of

Q162. A 1000VA transformer has 1000 turns in the primary and 100 turns in the secondary. A primary voltage of 120V is applied to the primary. What is the secondary voltage of the transformer?

- (a) 120V
- (b) 12V
- (c) 132V
- (d) 220V

Q163. Wagner's earth devices are used in AC bridge Circuit for-

- (a) Eliminating the effect of earth capacitances
- (b) Eliminating the effect of inter component capacitances
- (c) Shielding the bridge elements
- (d) Eliminating the effect of stray electrostatic fields

Q164. A vector impedance meter measures

- (a) The phase angle of the impedance
- (b) The power dissipation in the impedance
- (c) The magnitude of impedance
- (d) Both the magnitude and phase angle of the impedance

Q165. Accuracy of an instrument means _____

- (a) Repeatability of the measured value
- (b) Closeness of the indicated by it to the correct value of measured
- (c) Smallest change in the value of measured that can be detected by the instrument
- (d) Speed with which the instruments reading approaches the final value

Q166. If an ammeter is to be used in place of a voltmeter, we must connect with the ammeter a

- (a) low resistance in parallel
- (b) low resistance in series
- (c) high resistance in parallel
- (d) high resistance in series

Q167. While using a wattmeter, which of the following conditions should be satisfied? to wattmeter

- (a) P.F is 0.6 or less
- (b) PF is unity
- (c) Load is balanced
- (d) The load is non-inductive

Q168. A voltmeter has a full scale deflection current of 10 mA and an internal resistance of 1000 Ω .

- (a) Accuracy is 1%
- (b) Resolution is 1 mV
- (c) Draws 10 mA at full scale
- (d) Creates 10 V drop at full scale

Q169. An ammeter has a full scale deflection current of 10 mA and an internal resistance of 1000 Ω .

- (a) Very low resistance
- (b) Low value of resistance
- (c) High value of resistance
- (d) None of the above

Q170. The range of an ammeter can be increased by: be increased

- (a) connecting a high resistance in series with the instrument
- (b) connecting a low resistance in series with the instrument
- (c) connecting a low resistance in parallel with the instrument
- (d) connecting a high resistance in parallel with the instrument

Q171. Copper shading is provided in energy meter to

- (a) To increase speed of aluminium disc
- (b) To balance the system from vibration
- (c) Bring flux exactly in quadrature with applied voltage
- (d) None of the above

Q172. The merging of a free electron and a hole is known as

- (a) Recombination
- (b) Extrusion
- (c) Absorption
- (d) Adsorption

Q173. An intrinsic semiconductor has equal number of electrons and holes in it. This is due to

- (a) Free electrons
- (b) Thermal energy
- (c) Doping
- (d) Valence

Q174. Resistivity

- (a) Increases with temperature
- (b) Decreases with temperature
- (c) First increases and then decreases with temperature
- (d) No change with temperature

Q175. The dielectric constant

- (a) Is proportional to the square of the electric field
- (b) Is independent of the electric field
- (c) Increases with the electric field at higher values of electric field
- (d) Increases with the electric field at low values and gradually decreases at higher values of electric field.

Q176. The built-in potential of a silicon pn junction is,

- (a) 0.3 V, 0.7 V
- (b) 0.5 V, 0.3 V
- (c) 0.7 V, 0.3 V
- (d) 0.5 V, 0.7 V

Q177. When a number is represented in 2's complement notation, the sign bit would have unique representation for zero.

- (a) Sign magnitude
- (b) 1's complement
- (c) 2's complement
- (d) 9's complement

Q178. What is the decimal equivalent of hexadecimal number 8A7 ?

- (a) 1422
- (b) 1242
- (c) 2114
- (d) 2215

Q179. What is the effect of Negative Feedback on the Amplifier?

- (a) There is a decrease in the gain of the Amplifier.
- (b) There is an increase in frequency.
- (c) There is a decrease in Bandwidth.
- (d) There is an increase in phase distortion.

Q180. If applied voltage on a motor is 200 volts and back emf is 150 volts, the efficiency of the motor is-

- (a) 100%
- (b) 80%
- (c) 50%
- (d) 75%

Q181. A direct current motor takes 10 A at 110 V and draws 4 amp current at 1000 rpm. The mechanical power developed is

- (a) 880
- (b) 1000
- (c) 100
- (d) 1100

Q182. Permanent magnet motor is also known as:

- (a) Shunt excitation
- (b) Series excitation
- (c) Separately excited
- (d) Compound excitation

Q183. In parallel operation, the generator is normally preferred

- (a) Series
- (b) Shunt
- (c) Under compound
- (d) Both shunt and series

Q184. In the case of parallel operation of DC compound wound generators for proper division of load from no load to full load it is essential that they should have the same

- (a) Series field resistance
- (b) Speed of operation
- (c) Percentage regulation
- (d) None of the above

Q185. A separately excited DC generator has induced emf of 250 V and full load terminal voltage of 240 V. if the value of armature resistance is 0.2Ω . Find the output of generator.

- (a) 10 KW
- (b) 12 KW
- (c) 15 KW
- (d) 18 KW

Q186. In a shunt generator the voltage build up is generally restricted by

- (a) Saturation of iron
- (b) Speed limitation
- (c) Armature heating
- (d) Insulation restriction

Q187. For a

- (a) 6V
- (b) 10.23 V
- (c) 2 V
- (d) 7.8 V

Q188. The transfer characteristic of a common emitter amplifier is

- (a) $\frac{-2I_{DSS}}{V_P} \left[1 - \left(\frac{V_{DS}}{V_P} \right)^2 \right]$
- (b) $\frac{-2I_{DSS}}{V_P} \left(1 - \frac{V_{DS}}{V_P} \right)$
- (c) $\frac{-2I_{DSS}}{V_P} \left(1 - \frac{V_{DS}}{V_P} \right)^2$
- (d) None of these

Q189. For transistor configured as a common emitter amplifier $\beta = 40$ and $A_{v_{mid}} = 100$. Base current (I_B) = $25 \mu A$. What is the value of emitter current (I_E)

- (a) 10.25 mA
- (b) 1.025 mA
- (c) 102.5 mA
- (d) 1025 mA

Q190. The method suitable for heating of conducting medium is ____.

- (a) Induction heating
- (b) Indirect arc heating
- (c) Eddy current heating
- (d) Radiant heating

Q191. In an electrical heating process, the high frequency capacitive heating is also known as:

- (a) Infrared heating
- (b) Dielectric heating
- (c) Induction heating
- (d) Resistance heating

Q192. For arc heating, the electrodes used are made of

- (a) Graphite
- (b) Tungsten
- (c) Copper
- (d) Iron

Q193. The basic elements of an electric drive are

- (a) Electric motor and the transmission system
- (b) Electric motor, the transmission and control system
- (c) The transmission and control system
- (d) Electric

Q194. The r

- (a) It is cum
- (b) It is cost
- (c) Electric p
- (d) None of

Q195. In wh double or the r oval shape
cable is used

- (a) Cleat wir
- (b) Casing a
- (c) Batten w
- (d) Conduit

Q196. As pe the red on voltage line is

- (a) 0 to 230 V
- (b) 230 V to 6
- (c) 650 V to 1
- (d) Above 10

Q197. How

- (a) One
- (b) Two separate and distinct
- (c) Three separate and distinct
- (d) All of above

Q198. What is the dimension of the copper strips used for the strip earthing

- (a) 25 mm × 4 mm
- (b) 25 mm × 3 mm
- (c) 25 mm × 2 mm
- (d) 25 mm × 1 mm

Q199. To prevent the decaying owing to snow and rain, the wooden poles are protected by _____ cap at the top.

- (a) Aluminium
- (b) Zinc
- (c) Cement
- (d) All of above

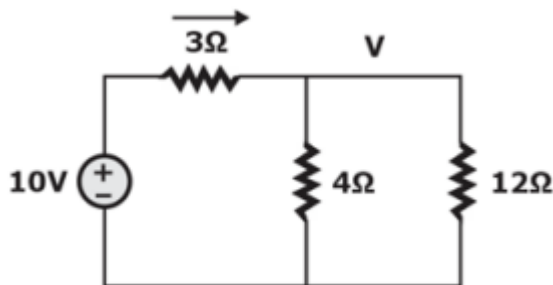
Q200. The safety factor used for the current rating in a power installation is ____

- (a) 0.5
- (b) 1
- (c) 1.5
- (d) 2

SOLUTIONS

S101. Ans.(c)

Sol.



$$\frac{V-10}{3} + \frac{V}{4} = 0$$

$$4V - 40 + 3V = 0$$

$$7V = 40$$

$$V = 5.71 \text{ V}$$

The current in the resistor 3Ω is $\frac{V-10}{3} = \frac{-4.29}{3} = -1.43 \text{ A}$

Power absorbed by 3Ω resistance $= I^2 R = \left(\frac{5}{3}\right)^2 \times 3 = 8.33 \text{ W}$

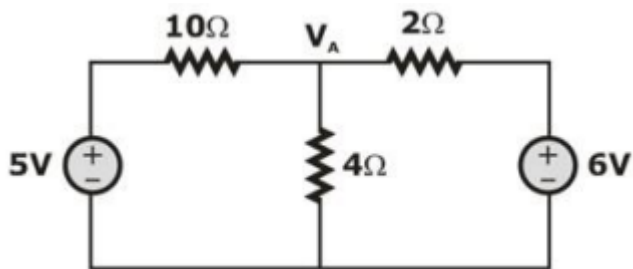
S102. Ans.(c)

Sol. Delta or Mesh Connection System is also called Three Phase Three Wire System (3-Phase 3 Wire) and it is the best and suitable system for AC Power Transmission. A distribution transformer with a delta primary,

running on three 20kV phases with no neutral or earth required, and a star secondary providing a 3-phase supply at 400 V, with the domestic voltage of 230 available between each phase and an earthed neutral point.

S103. Ans.(b)

Sol.



Applying KCL at node A

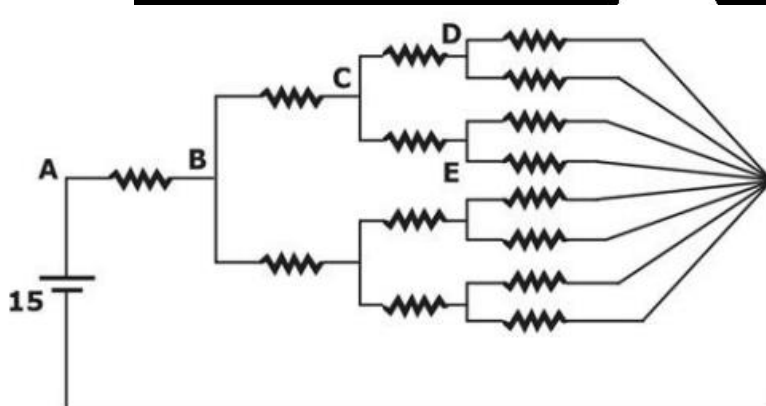
$$\frac{V_A - 5}{10} + \frac{V_A}{4} = 0$$

$$V_A = 4.7V$$

Current is 4A

S104. Ans.(c)

Sol.



$$R_{DF} = 1\Omega \parallel 2\Omega = 1\Omega$$

$$R_{CF} = 1\Omega \parallel 2\Omega = 1\Omega$$

$$R_{BF} = 1\Omega \parallel 2\Omega = 1\Omega$$

$$R_{AF} = 1\Omega \parallel 2\Omega = 1\Omega$$

$$i = \frac{15}{3.75}$$

$$i = 4A$$

S105. Ans.(d)

Sol.

$$\text{Given, } v(t) = 50\sin(13t - 20)V$$

$$\text{at } t = 5$$

$$v(t) = 50\sin(13 \times 5 - 20)V$$

$$= 50\sin(65 - 20)V$$

$$= 50\sin 45^\circ$$

$$= 35.35 V$$

S106. Ans.(d)

Sol. In the circuit

$$L_{eq} = L_1 + L_2 + 2m \quad (M = \text{mutual inductance})$$

$$m = K\sqrt{L_1 L_2}$$

$$x_m = \omega m = K\sqrt{\omega L_1 \cdot \omega L_2}$$

$$= K\sqrt{9 \times 4} = 6K$$

Also

$$X_L = X_{L1} + X_{L2} + 2X_m = 9 + 4 + 12K$$

$$= 13 + 12K$$

At series resonance

$$X_C = X_L$$

$$30 = 13 + 12K$$

$$K = \frac{17}{12}$$

which is not possible.

S107. Ans.(c)

Sol. A.C. ammeter measures

$$I_{rms} = \sqrt{\frac{1}{T} \int_0^T i^2 dt}$$

$$= \sqrt{\frac{1}{1} \int_0^1 15.4^2 dt} = 11.54 \text{ A}$$

S108. Ans.(c)

Sol. Tellegen's theorem is applicable to any network, whether linear or non-linear, active or passive, time-variant or time-invariant. Tellegen's theorem states that the sum of instantaneous power consumed in various elements in various meshes is zero in any network. This theorem is based on the principle of conservation of energy, which applies to all systems, whether they are linear or non-linear. On the other hand, Thevenin's theorem is applicable to any network of resistors, voltage sources, and current sources.

S109. Ans.(d)

Sol. In a series RLC circuit, if $X_C > X_L$, then the Current will lead the supply voltage.

S110. Ans.(c)

Sol. Conductance (G) = $\frac{1}{\text{Resistivity (R)}}$

↓

$$\text{Unit} = \frac{1}{\text{ohm}} \text{ (mho or siemen)}$$

S111. Ans.(d)

The law that states that in any closed circuit the current is directly proportional to the voltage, provided the physical conditions of the circuit are kept constant is Ohm's law.

$$V \propto I \text{ (physical conditions constant)}$$

↓

Ohm's law

S112. Ans.(b)

The potential inside a charged hollow sphere is constant and equal to the potential on the surface.

Inside a charge hollow sphere

$$E = 0$$

and Electric

So, $V = \text{Const}$

S113. Ans.(c)

Sol. Paramagnetic materials are slightly attracted by magnetic materials it is less than diamagnetic materials.

S114. Ans.(c)

Sol. Magnetic field lines are closed. Magnetic field lines start from the north pole of a magnet and end at the south pole of a magnet. The negative end of a current-carrying wire is because magnetic field lines do not have any starting or ending point.

S115. Ans.(c)

Sol. for HWB $= \frac{I_m}{2}$

$$\Rightarrow 20 = \frac{I_m}{2}$$

$$\Rightarrow I_m = 40 \text{ A}$$

For FWR: I_{rms}

S116. Ans.(c)

Sol.

Energy = Power $\times$ time

$$E = 2 \times 1000 \times 10 \times 60$$

$$E = 2 \times 1000 \times 10 \times 6$$

$$E = 12,00,000 \text{ J}$$

$$E = 1200 \text{ kJ}$$

Alternate information:

$$1 \text{ kWh} = 3.6 \times 10^6 \text{ Joules}$$

$$= 3.6 \text{ Mega Joule}$$

S117. Ans.(c)**Sol.**

We know that $C = \frac{Q}{V}$

$$C = \frac{\epsilon_0 A}{d}$$

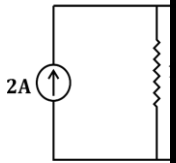
Where, A = the area of each plate
 d = distance between the plate
 $C \propto A$

If area is four times the capacitance will be four times

S118. Ans.(c)**Sol.** Field due to

Amp/meter

$$= \frac{NI}{\ell} \text{ (Turn-)}$$

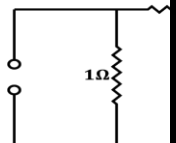
S120. Ans.(c)**Sol.** Remove

$$V_{oc} = 5 \text{ V}$$

For R_{th}

Current source

Voltage source



$$R_{th} = 0 || 3 = 0$$

$$\therefore I_{5\Omega} = \frac{V_{oc}}{R_{th} + 5}$$

$$\therefore V_{th} = 5 \text{ V}$$

$$R_{th} = 0 \Omega$$

$$I_{5\Omega} = 1 \text{ A}$$

S121. Ans.(d)

Sol. It is possible to reduce the proximity effect by reducing the size of the conductor and the frequency and by increasing the voltage and space between conductors.

S122. Ans.(c)

Sol. Given: Maximum load = 5MW, Average load = 2800 kW

$$\text{Load factor} = \frac{\text{Average load}}{\text{Maximum demand}} = \frac{2800 \times 10^3}{5 \times 10^6} = 0.56$$

S123. Ans.(b)

Sol. The Buchholz relay is primarily used to protect oil-filled transformers against internal faults, such as faults involving the transformer's insulation or the presence of gases generated due to internal arcing or overheating. Therefore, Oil-immersed transformers against all internal faults is the correct answer.

S124. Ans.(a)

Sol. String efficiency, $\eta = \frac{V}{nV_s} \times 100\%$

$$n = 5$$

$$V_s = 25\% \text{ of } V$$

(Where V = total string voltage)

$$\text{So, } \eta =$$

$$= \frac{1}{5 \times 0.25}$$

S125. Ans.(c)

Sol. Surge Impedance

Z_0 is not function of frequency

$\therefore Z_0$ will remain constant

S126. Ans.(c)

Sol.

Full load slip

$\frac{\text{starting torque}}{\text{Full-load torque}}$

$$= (4)^2 \times 0.05$$

S127. Ans.(c)

Sol. a reluctance motor, the angle between the stator direct axis and quadrature axis is typically 90° .

This angle is called as load angle. The rotor axis is aligned with the stator direct axis.

Due to this angular displacement, the motor produces torque.

S128. Ans.(c)

Sol. universal motors are a type of electric motor that can operate on both AC (alternating current) and DC (direct current) power sources. They are known for their high speed and high torque characteristics, which make them suitable for applications requiring both high rotational speed and high torque output.

S129. Ans.(c)

Sol. Given,

$$f = 50 \text{ Hz}$$

$$P = 6$$

$$S = 3\% = 0.03$$

$$N_r (\text{Rotor Speed}) = ??$$

$$\text{Synchronous speed } (N_s) = \frac{120f}{P}$$

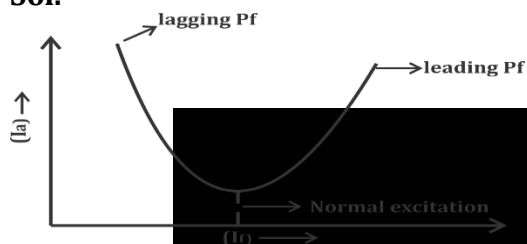
$$= \frac{120 \times 50}{6} = 1000 \text{ rpm}$$

Slip is given as, $S = \frac{N_s - N_r}{N_s}$

$$0.03 = \frac{1000 - N_r}{1000} \Rightarrow N_r = 970 \text{ rpm}$$

S130. Ans.(b)

Sol.



If we increase the field current, the armature current will increase. When the motor is under-excited, the power factor is lagging. When the motor is over-excited, the power factor is leading. At normal excitation, the power factor is unity.

S131. Ans.(c)

Sol. Synchronous motor can be made to operate as a generator. Following are the advantages of synchronous motor:

- Provides constant speed.
- Reduce the size of the motor.
- Used for power factor correction.
- Under no-load condition, the motor can be used as a generator. The current becomes zero.

S132. Ans.(c)

Sol.

Power

We know that

$$\text{Synchronous speed } (N_s) = \frac{120f}{P} = \frac{120 \times 50}{12} = 500 \text{ rpm}$$

$$\text{Torque developed } T = \frac{P}{\frac{2\pi N_s}{60}} = \frac{60968}{2\pi \times \frac{500}{60}} = 1164.4 \text{ Nm}$$

S133. Ans.(d)

Sol. On the sudden application of load, the rotor searches for its new equilibrium position and starts oscillating. The phenomenon of oscillation of the rotor about its final equilibrium position is called **Hunting**.

• Hunting is a process occurs in a synchronous motor as well as in synchronous generators on an abrupt change in load.

S134. Ans.(a)

Sol.

$$N_s = \frac{120f}{P} = 600 \text{ rpm}$$

$$\text{If } f = 50 \text{ Hz then } P = \frac{120 \times 50}{600} = 10$$

$$\text{If } f = 60 \text{ Hz then } P = \frac{120 \times 60}{600} = 12$$

S135. Ans.(c)

Sol. When a 3-phase synchronous motor is switched ON, there exists a rotating magnetic field. The magnitude of this field is directly proportional to the supply voltage.

S136. Ans.(c)

Sol.

Step Angle (α)

$$m = 3, N_r = 20$$

$$(\alpha) = \frac{360^\circ}{3 \times 20} = 6^\circ$$

S137. Ans.(c)

Sol. A shaded pole synchronous motor is composed of two main parts, a stator and a rotor. The stator is composed of copper ring and is divided into two main parts, the main pole and the shaded pole. The shaded pole is composed of a copper ring and is divided into two main parts, the main pole and the shaded pole. And their ratio is 1:5 to 350%.

S138. Ans.(c)

Sol. In India, the maximum transmission voltage is 765 kV. The power grid is connected to these lines for interstate transmission throughout the entire nation.

S139. Ans.(c)

Sol. In AC the power factor is the ratio of real power to complex power. The power factor is the ratio of real power to complex power. The power factor decreases as the power factor increases. The power factor is the ratio of real power to complex power.

$$P = V_L I_L \cos \phi$$

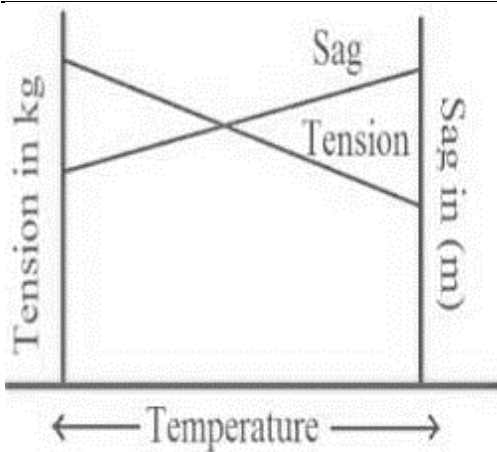
$$I_L = \frac{P}{V_L \cos \phi}$$

$$I_L \propto \frac{1}{\cos \phi}$$

S140. Ans.(a)

Sol. Stringing chart gives the data per sag to be allowed and the tension to be allowed in a transmission line for a particular temperature.

It represents a graph of sag and tension V/S temperature.



S141. Ans.(c)

Sol. In a transmission line, the greater is the temperature, the greater is the sag and the lesser is the tension. Hence, sag is used for the design of conductors.

S142. Ans.(c)

Sol. The correction factor for sag is directly proportional to the temperature.

P_c (correction factor)

for f_d

$$\frac{P_{DC}}{P_{AC}} =$$

$$P_{DC} =$$

Therefore, correction factor

S143. Ans.(c)

Sol. High voltage DC transmission is more efficient than AC transmission. HVDC transmission provides greater stability, reliability and transmission capacity. AC transmission has more line losses than DC.

S144. Ans.(c)

Sol. The skin effect is the tendency of the current to be concentrated near the surface of the conductor, rather than being evenly distributed throughout its cross-section. This effect depends on several factors including.

- (a) frequency
- (b) permeability of conductor
- (c) cross-sectional area of conductor
- (d) temperature of the conductor

S145. Ans.(b)

Sol. Inductance of power transmission line increases with increase in spacing between phase conductors.

$$L = \frac{\mu_0}{2\pi} \log \left(\frac{d}{r} \right)$$

S146. Ans.(d)

Sol. In ac distribution system the voltage can be controlled by using

1. Induction regulator
2. Booster transformer
3. Tap changing transformer

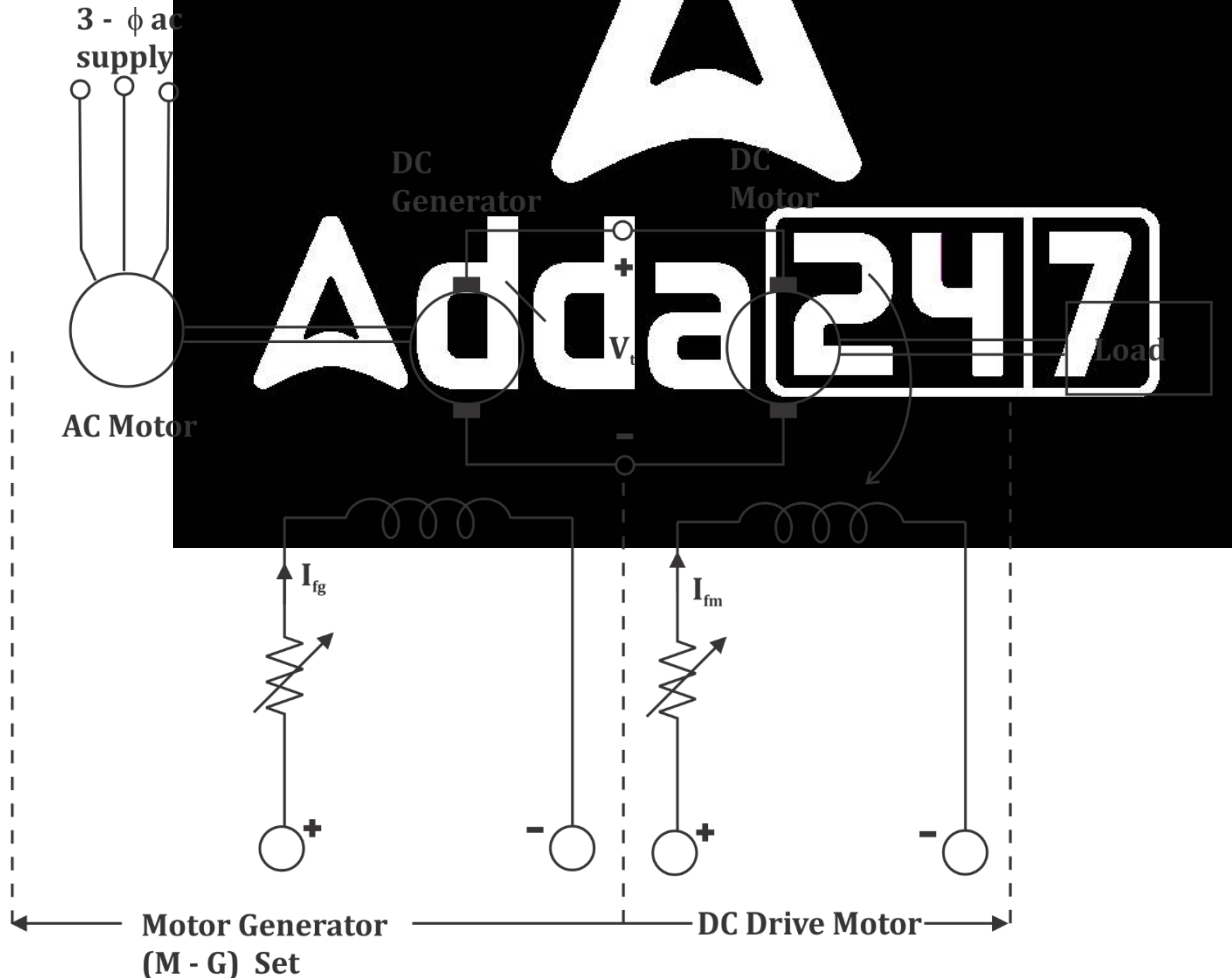
S147. Ans.(d)

Sol. The rating of a bus bar is determined by several factors, including current, voltage, frequency, and short-circuit current.

S148. Ans.(d)

Sol. The speed of a synchronous motor can be controlled by the Ward-Leonard method. Ward-Leonard system was developed by Ward in 1891. In this system, a synchronous motor is mechanically coupled to a DC generator. The DC generator is excited by a DC source. The DC generator is connected to a DC motor, which is connected to the load. The speed of the DC motor is controlled by the field current of the DC generator.

DIAGRAM V



S149. Ans.(a)

Sol. Speed control by varying the resistance in the armature circuit varies the hardness of the speed-torque characteristics and therefore results in a different stability of operation for a given speed. This type of control is used to reduce the speed below the base speed at constant load torque.

S150. Ans.(b)

Sol. In slip ring induction motor rotor has winding on it. If no of the poles of the stator is changed then then we have to change design of rotor winding to make rotor poles equal to stator winding. Hence, Changing the pole method is not used for controlling the speed of the slip ring induction motor.

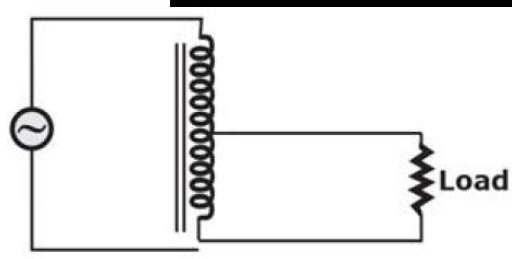
S151. Ans.(c)

Sol. Surge in

- The insula

S152. Ans.(c)

Sol.



In an auto transformer, the primary and secondary windings are used for both the primary and secondary windings. But in a conventional transformer, the primary and secondary windings are used for both the primary and secondary windings.

Advantage of auto transformer is that it is more efficient than a conventional transformer. Its efficiency is more when compared with the conventional transformer.

- Its efficiency is more when compared with the conventional transformer.
- Its size is relatively smaller.
- Voltage regulation is better.

S153. Ans.(c)

Sol. As short circuit current,

$$I_{sc} \propto \frac{1}{X_s}$$

Where, X_s is inductance of line

When fault is near to alternator, inductance value will be smaller as it is proportional in length of line. Hence, short circuit current will be higher.

S154. Ans.(b)

Sol. Given, base current, $I_b = 20 \mu A$

Given, base current, $I_b = 20 \mu A$

$$\alpha = 0.92$$

Collector current, $I_C = \beta I_b = \frac{\alpha}{1-\alpha} I_b$

$$I_C = \frac{0.92}{1-0.92} \times 20 \mu A$$

$$I_C = 230 \mu A$$

Emitter current, $I_E = I_C + I_b$

$$I_E = 230 \times 10^{-6} A + 20 \times 10^{-6} A$$

$$I_E = 250 \times 10^{-6} A$$

$$I_E = 0.25 mA$$

S155. Ans.(b)

Sol. Schottky diode is a metal-semiconductor function diode without depletion layer.

In Schottky diode, the depletion layer is formed in the metal side.

S156. Ans.(c)

Sol. Core loss

in flux linkages

S157. Ans.(c)

Sol. Adding load, the pf of the motor will still

work at lagging

S158. Ans.(c)

Sol. For a three phase motor, the slip at full load is

S159. Ans.(c)

Sol. For DC

$$V = 200 V$$

$$E = 198 V$$

$$R_a = 0.4 \text{ ohm}$$

$$I_a = \frac{200-198}{0.4}$$

S160. Ans.(c)

Sol. 2's complement

2's complement

$$2's \text{ complement of } 01101001 = 10010101$$

So, Ans is 10010101.

S161. Ans.(c)

Sol. Torque of dc series motor, $T = k_a \phi_{se} I_a$

$$\text{Now } = k_a k_{se} I_a^2$$

Here $k_a k_{se} = k \rightarrow \text{constant}$

$$T = k I_a^2$$

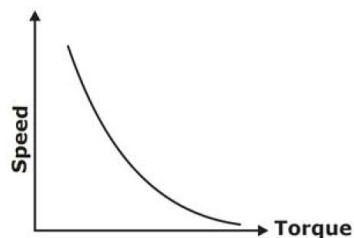
$$I_a = \sqrt{\frac{T}{k}}$$

$$\text{Now, } E = V - I_a(R_a + R_{se}) = k_n \phi_{se} N$$

$$\Rightarrow N = \frac{V}{k_n \phi_{se}} - \frac{I_n \cdot R_a}{k_n \phi_{se}} [R_a = r_a + r_{se}]$$

$$\Rightarrow N = \frac{V}{k_n \phi_{se}} - \frac{R_a}{k_n \phi_{se}}$$

There is inverse relation between torque and speed.



S162. Ans.(c)

Sol. For step

$$\frac{120+12}{120} = \frac{132}{120}$$

$$V_{\text{secondary}} =$$

$$V_{\text{secondary}} =$$

S163. Ans.(c)

Sol. For step

$$\frac{120+12}{120} = \frac{132}{120}$$

$$V_{\text{secondary}} =$$

S164. Ans.(c)

Sol. A vector

→ this method

the impedance

S165. Ans.(c)

Sol. Accuracy

closeness with

i.e. conform

S166. Ans.(d)

Sol. If an ammeter is to be used in place of a Voltmeter we must connected with ammeter a high resistance in series.

→ since resistance of voltmeter is very high and resistance of ammeter is less so when we replace voltmeter with ammeter we connect high resistance in series to protect ammeter.

S167. Ans.(d)

Sol.

$$\phi = \tan^{-1} \left[\sqrt{3} \left(\frac{w_1 - w_2}{w_1 + w_2} \right) \right]$$

$$w_2 = -w_1$$

$$\phi = \tan^{-1} \left[\sqrt{3} \left(\frac{w_1 + w_1}{w_1 - w_1} \right) \right]$$

$$\phi = \tan^{-1} \left[\sqrt{3} \left(\frac{2w_1}{0} \right) \right]$$

$$\phi = \tan^{-1} \infty$$

$$\tan \phi = \tan 90^\circ$$

$$\phi = 90^\circ$$

so the load is pure inductive.

S168. Ans.(c)

Sol. voltmeter having high internal resistance so it draws low current and correctly measure the potential difference.

S169. Ans.(c)

Sol. An ammeter is an instrument for measuring the electric current in amperes in a branch of an electric circuit. It must be placed in series with the measured branch, and must have very low resistance to avoid significant alteration of the current it is to measure.

S170. Ans.(c)

Sol. PMMC is used for measuring AC voltage. By connecting a capacitor across the instrument.

S171. Ans.(c)

Sol. Copper is used for winding of energy meter to bring the flux density in the air gap uniform. The purpose of this is to improve the accuracy of the measurement.

S172. Ans.(c)

Sol.

- When semiconductor is excited, it creates electron-hole pairs in the conduction band, leaving holes in the valence band.
- The orbits of the valence band overlap with the conduction band.
- one atom's conduction band intersects the entire orbit of another and electron from C.B. falls into a hole as a result of this.
- They merge of electron & hole call a Recombination

S173. Ans.(b)

Sol. An intrinsic semiconductor has equal number of electrons and holes in it. This is due to thermal energy. In an intrinsic semiconductor at thermal equilibrium, some electrons from the valence band are thermally excited to the conduction band, creating equal numbers of electrons and holes. This balance is achieved through the energy provided by thermal agitation. It does not depend on factors like free electrons, doping, or the specific characteristics of valence electrons.

S174. Ans.(b)

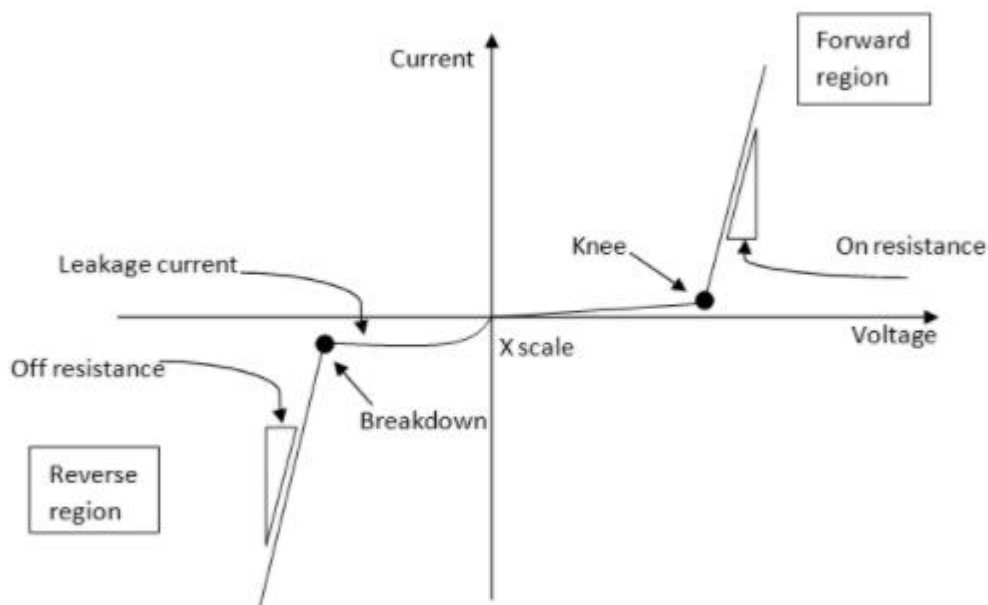
Sol. by adding impurities Resistance of semiconductor is decrease. Impurities such as Arsenic, Antimony, Phosphorous are added in N-type semiconductors. Impurities such as Aluminium, Gallium and Indium are added in P-type semiconductors.

S175. Ans.(d)

Sol. In silicon, the drift velocity of electrons initially increases linearly with the electric field at lower values of the field strength. However, as the electric field strength increases, the drift velocity begins to saturate and doesn't increase linearly anymore.

S176. Ans.(c)

Sol. The known threshold voltage of a PN junction is the point at which a PN junction starts to conduct. The threshold voltage for Silicon PN junction is approximately 0.7V. When the voltage reaches approximately 0.7V, the current begins to increase significantly. For Germanium, the threshold voltage is lower, approximately 0.3V. For silicon, the current begins to increase significantly after the voltage reaches approximately 0.7V. For Germanium, the current begins to increase significantly after surpassing the threshold voltage of approximately 0.3V.



S177. Ans.(c)

Sol. In binary arithmetic, when signed numbers are used, the 2's complement notation has a unique representation for zero. The 2's complement representation is commonly used because it has the advantage of having a unique representation for zero and simplifies arithmetic operations like addition and subtraction.

S178. Ans.(d)

Sol. To convert a hexadecimal number to its decimal equivalent,

$$8A7 \text{ (hexadecimal)} = (8 \times 16^2) + (A \times 16^1) + (7 \times 16^0)$$

Now, in hexadecimal, A represents the decimal value 10.

$$(8A6)_{16} = (8 \times 256) + (10 \times 16) + (7 \times 1)$$

$$(8A6)_{16} = 2048 + 160 + 7$$

$$(8A6)_{16} = (2215)_{10}$$

So, the decimal equivalent of the hexadecimal number 8A6 is 2215.

S179. Ans.(c)

Sol. We know

$$A_f =$$

Negative feedback

S180. Ans.(c)

Sol. Given, $V_b = 150 \text{ V}$

$$E_b = 150 \text{ V}$$

Power output

$$\eta\% = \frac{\text{power out}}{\text{Power in}}$$

S181. Ans.(c)

Sol.

Given that

$$I_a = 4 \text{ A}$$

$$R_a = 5 \Omega$$

$$V = 220 \text{ V}$$

$$\therefore V = E_b + I_a R_a$$

Back emf (E_b)

$$E_b = 220 - 4 \times 5$$

Input power

$$= 220 \times 4 +$$

S182. Ans.(c)

Sol. Permanent magnet excitation is also known as Separate excitation. In separate excitation, a separate source of excitation, such as a permanent magnet, is used to create the magnetic field in a DC machine or motor, independent of the armature current. This allows for control of the field strength and, consequently, the motor's performance.

S183. Ans.(d)

Sol. DC shunt & under compound DC generators due to their drooping characteristics are best suited for parallel operation.

S184. Ans.(c)

Sol. For satisfactory operation, it is durable that all the machines operating in parallel should have same percentage voltage regulation so as to share the total load in proportion to their rated capacity.

S185. Ans.(b)

Sol.

$$E_g = 250 \text{ V} \quad V_t = 240 \text{ V}$$

$$R_a = 0.2 \, \Omega$$

$$E_g = V_t + I_a R_a$$

$$250 = 240 + I_a \times 0.2$$

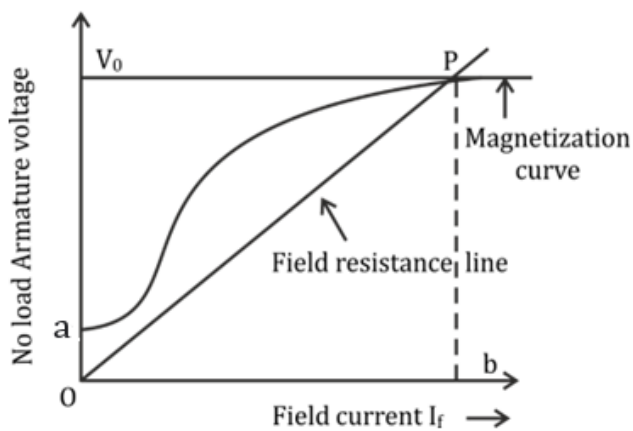
$$I_a = \frac{250 - 240}{0.2}$$

$$\text{Output} = V_t I_a$$

$$= 240 \times 50 =$$

S186. Ans.(c)

Sol. In a shunt generator, the terminal voltage will get slightly less than the no-load voltage. Once the load is increased, the terminal voltage will get slightly lower than the no-load voltage. Any further increase in field current will not increase the terminal voltage.

**S187. Ans.(c)**

Sol. $V_{GS} = 3V$, $I_{DSS} = 6A$ and $I_D = 3A$

$$I_D = I_{DS} \left(1 - \frac{V_{GS}}{V_P}\right)^2$$

$$3 = 6 \left(1 - \frac{3}{V_P}\right)^2$$

$$\frac{3}{6} = \left(1 - \frac{3}{V_P}\right)^2$$

$$\frac{1}{\sqrt{2}} = 1 - \frac{3}{V_P}$$

$$1 - \frac{1}{\sqrt{2}} = \frac{3}{V_P}$$

$$V_P = 10.23V$$

S188. Ans.(a)

Sol. Drain to source current is

$$\bullet I_{DS} = I_{DSS} \left(1 - \frac{V_{GS}}{V_P}\right)^2$$

Transconductance is

$$\bullet g_m = \frac{\partial I_D}{\partial V_{GS}}$$

$$g_m = \frac{-2I_{DSS}}{V_P} \left(1 - \frac{V_{GS}}{V_P}\right)$$

S189. Ans.(b)

Sol. Current

Base current

Emitter current

$$\beta = \frac{I_C}{I_B}$$

$$I_C = \beta I_B = 4$$

$$I_C = 10^{-3} A$$

$$I_E = I_C + I_B$$

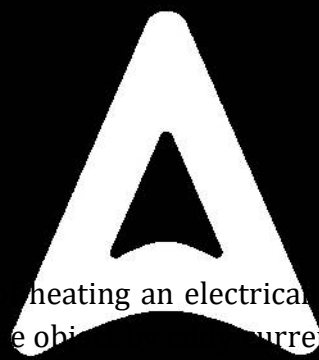
$$I_E = 1mA +$$

S190. Ans.(c)

Sol. Induction

induction, the

of conducting



Adda247

S191. Ans.(c)

Sol. The process of heating in which a high-frequency alternating electric field of radio waves or microwave electromagnetic radiation are used to heat the dielectric materials is known as dielectric heating.

Dielectric heating

Dielectric heating

Dielectric heating

S192. Ans.(a)

Sol. graphite is the most commonly used material for arc electrodes due to its high melting point, low reactivity, and ability to conduct electricity. Graphite electrodes are widely used in applications such as steelmaking, metalworking, and glass manufacturing.

Arc heating is a process that involves the use of an electric arc to heat or melt a material. The electric arc is generated between two electrodes, which are typically made of materials that can withstand high temperatures and resist melting or vaporization.

Arc heating is a process that involves the use of an electric arc to heat or melt a material. The electric arc is generated between two electrodes, which are typically made of materials that can withstand high temperatures and resist melting or vaporization.

Arc heating is a process that involves the use of an electric arc to heat or melt a material. The electric arc is generated between two electrodes, which are typically made of materials that can withstand high temperatures and resist melting or vaporization.

Arc heating is a process that involves the use of an electric arc to heat or melt a material. The electric arc is generated between two electrodes, which are typically made of materials that can withstand high temperatures and resist melting or vaporization.

Arc heating is a process that involves the use of an electric arc to heat or melt a material. The electric arc is generated between two electrodes, which are typically made of materials that can withstand high temperatures and resist melting or vaporization.

S193. Ans.(b)

Sol. The basic elements of an electric drive are Electric motor, the transmission, and control system.

S194. Ans.(c)

Sol. The main drawback of electric drive is that Electric power supply failure makes the drive standstill.
It has a poor dynamic response
It cannot install where electricity is not available.

S195. Ans.(c)

Sol. Batten wiring is basically an internal wiring system and are of two types:

- CTS or TRS or PVC sheath wiring
- Lead sheathed or metal sheathed wiring

CTS cables are available in single-core, twin-core or three core with a circular or oval in shape.

S196. Ans.(c)

Sol. As per IS 1956

- Low voltage
- Medium voltage
- High voltage
- Extra high voltage

S197. Ans.(c)

Sol. As per IS 1956, the separate and distinct earth connection will be provided for the separate and distinct earth connection.

S198. Ans.(c)

Sol. Copper will be the best material for the connection of the cable.

S199. Ans.(c)

Sol. Wooden poles are used in power distribution systems and are often protected and covered by snow and rain by the use of various methods. One common method is to install a cap on the pole. These caps can be made of different materials such as aluminum, zinc, or steel. The purpose of the cap is to protect the wood from weathering and prevent it from rotting. The cap also helps in preventing the wood from being used as a protective cover for the pole.

S200. Ans.(d)

Sol. The safety factor used for the current rating in a power installation is 2.